

# Supplement to Operating Manual

## R&S Signal Generator

Firmware Version 2.05.200 and higher

The new firmware version for the R&S Signal Generator offers Remote Control via LAN Interface using Telnet protocol as a new functionality that could not be reported yet in the current operating manual. The following description is to provide you with comprehensive information about these new features.

### Table of contents

<b>Remote Control via LAN Interface using Telnet protocol .....</b>	<b>2</b>
Setting up a Telnet Connection .....	2
Program examples .....	4

## Remote Control via LAN Interface using Telnet protocol

The instrument is equipped with the following interfaces for remote control:

- ◆ IEC/IEEE bus interface according to standard IEC 625.1/IEEE 488.2.
- ◆ LAN interface: the network card uses 10/100/1000Mbps Ethernet IEEE 802.3u; two protocols are supported:
  - the VXI-11 standard, using VISA
  - a simple telnet protocol, also called "Raw Ethernet".

The connectors are located at the rear of the instrument and permit a connection to a controller for remote control either via GPIB or via a local area network (LAN).

A VISA installation on the controller is a prerequisite for remote control over LAN (when using VXI-11 protocol).

Another alternative way to remote control the instrument is using a simple telnet protocol (port 5025). Unlike using the VXI-11 protocol, no VISA installation is necessary on the remote controller side.

This protocol is sometimes also referred as "socket communication" or "Raw Ethernet mode".

To control the instrument manually, only a Telnet program is required. The Telnet program is part of every operating system.

### Setting up a Telnet Connection

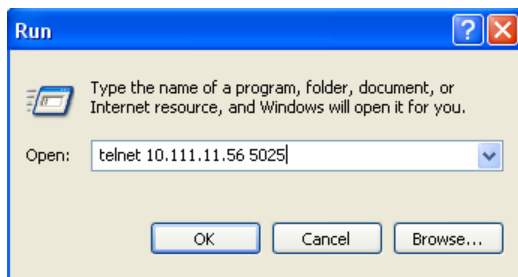
1. To establish a Telnet connection with an instrument, start the Telnet program, enter the IP address of the R&S Signal Generator and the number of the port configured for remote-control via Telnet.

---

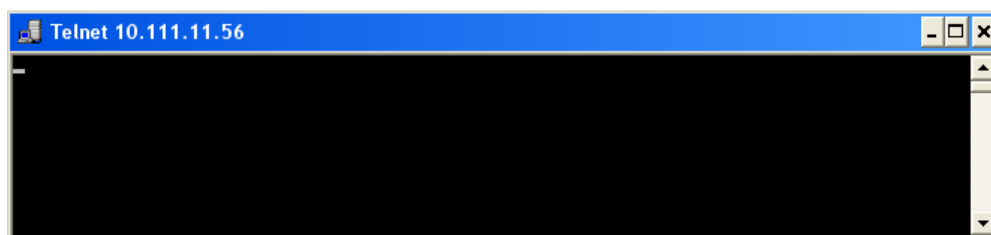
*Note:*

*The R&S Signal Generator uses the port number 5025 for remote connection via Telnet.*

---



The connection to the instrument is set up and remote-control commands can be sent.



- 2. Even if the cursor is not visible on the screen, enter blind a remote-control command and confirm with Enter.



After the first remote-control command had been send, the R&S Signal Generator is in the REMOTE state, i.e. instrument control from the front panel or via mouse and keyboard is disabled and REMOTE is displayed in the status line.

## Program examples

To write a program, only a socket communication must be established. The following program example shows a simple TcpClient class and how to use it.

```

#include <string>
//defines structs for socket handling
#include <netinet/in.h>
using namespace std;
typedef struct sockaddr_in SockAddrStruct;
typedef struct hostent      HostInfoStruct;
class TcpClient
{
public:
    TcpClient();
    ~TcpClient();
    void connectToServer( string &hostname, int port );
    void disconnect( );
    void transmit( string &txString );
    void receive( string &rxString );
    string getCurrentHostName( ) const;
    int    getCurrentPort( ) const;
private:
    string      currentHostName;
    int         currentPort;
    int         currentSocketDescr;
    SockAddrStruct  serverAddress;
    HostInfoStruct * currentHostInfo;
    bool        clientIsConnected;
    int         receiveBufferSize;
};

#include <netdb.h>
#include <netinet/in.h>
#include <unistd.h>
#include "TcpClient.h"
TcpClient::TcpClient()
: currentHostName( "" )
, currentPort( 0 )
, currentSocketDescr( 0 )
, serverAddress ( )
, currentHostInfo( NULL )
, clientIsConnected( false )
, receiveBufferSize( 1024 )
{
}
TcpClient::~~TcpClient()
{
    currentHostInfo = NULL;
}

void TcpClient::connectToServer( string &hostname, int port )
{
    currentHostInfo = gethostbyname( hostname.c_str( ) );
    if( currentHostInfo == NULL )
    {
        currentHostName = "";
        currentPort = 0;
        currentHostInfo = NULL;
        clientIsConnected = false;
        printf("error connecting host\n" );
    }
}

```

```

currentHostName = hostname;
currentPort      = port;
currentSocketDescr = socket(AF_INET, SOCK_STREAM, 0);
if( currentSocketDescr == 0 )
{
    currentHostName = "";
    currentPort      = 0;
    currentHostInfo  = NULL;
    clientIsConnected = false;
    printf("can't create socket\n" );
}
serverAddress.sin_family = currentHostInfo->h_addrtype;
serverAddress.sin_port   = htons( currentPort );
memcpy( (char *) &serverAddress.sin_addr.s_addr, currentHostInfo->h_addr_list[0],
currentHostInfo->h_length );
if( connect( currentSocketDescr, ( struct sockaddr *) &serverAddress, sizeof(
serverAddress ) ) < 0 )
{
    throw string("can't connect server\n" );
}
clientIsConnected = true;
}
void TcpClient::disconnect( )
{
    if( clientIsConnected )
    {
        close( currentSocketDescr );
    }
    currentSocketDescr = 0;
    currentHostName    = "";
    currentPort        = 0;
    currentHostInfo    = NULL;
    clientIsConnected  = false;
}
void TcpClient::transmit( string &txString )
{
    if( !clientIsConnected )
    {
        throw string("connection must be established before any data can be sent\n");
    }
    char * transmitBuffer = new char[txString.length() +1];
    memcpy( transmitBuffer, txString.c_str(), txString.length() );
    transmitBuffer[txString.length()] = '\n'; //newline is needed!
    if( send( currentSocketDescr, transmitBuffer, txString.length() + 1, 0 ) < 0 )
    {
        throw string("can't transmit data\n");
    }
    delete [] transmitBuffer;
}
void TcpClient::receive( string &rxString )
{
    if( !clientIsConnected )
    {
        throw string("connection must be established before any data can be received\n");
    }
    char * receiveBuffer = new char[receiveBufferSize];
    memset( receiveBuffer, 0, receiveBufferSize );
    bool receiving = true;
    while( receiving )
    {
        int receivedByteCount = recv( currentSocketDescr, receiveBuffer,
receiveBufferSize, 0 );
        if( receivedByteCount < 0 )
        {
            throw string("error while receiving data\n");
        }
    }
}

```

```

    rxString += string( receiveBuffer );
    receiving = ( receivedByteCount == receiveBufferSize );
}
delete [] receiveBuffer;
}
string TcpClient::getCurrentHostName( ) const
{
    return currentHostName;
}
int TcpClient::getCurrentPort( ) const
{
    return currentPort;
}

#include <iostream>
#include "TcpClient.h"
void printUsage()
{
    cout<<"usage: EthernetRawCommand <server-ip> [scpi-command]"<<endl;
}
int main( int argc, char *argv[] )
{
    int errorCode          = 0; //no error
    bool useSingleCommand = false;
    string singleCommand  = "";
    string hostname       = "";
    int    port           = 5025;
    string input          = "";
    TcpClient client;
    switch( argc )
    {
        case 3:
            useSingleCommand = true;
            singleCommand    = argv[2];
        case 2:
            hostname        = argv[1];
            break;
        default:
            printUsage();
            return(-1);
    }
    try
    {
        client.connectToServer( hostname, port );
        bool terminate = false;
        while( !terminate )
        {
            char buffer[1024];
            if( useSingleCommand )
            {
                input = singleCommand; //send string
            }
            else
            {
                cin.getline( buffer, 1024 );
                input = buffer;
                if( input == "end" )
                {
                    terminate = true;
                }
            }
        }
        if( !terminate)
        {
            client.transmit( input ); //send string
            int qPos = input.find( "?", 0 );
            //receive string only when needed

```

```
        if( qPos > 0 )
        {
            string rcStr = "";
            client.receive( rcStr );
            cout << rcStr << endl;
        }
    }
    if( useSingleCommand )
    {
        terminate = true;
    }
}
} catch( const string errorString )
{
    cout<<errorString<<endl;
}
client.disconnect( );
return errorCode;
}
```